

Digital Image Processing

Morphological Image Processing (2)

Topics

- Morphological Operations
 - Connected Component Extraction
 - Convex Hull
 - Thinning
 - Thickening
 - Skeleton
 - Pruning
 - Extension to gray level images
 - Matlab Examples

Dilation and Erosion

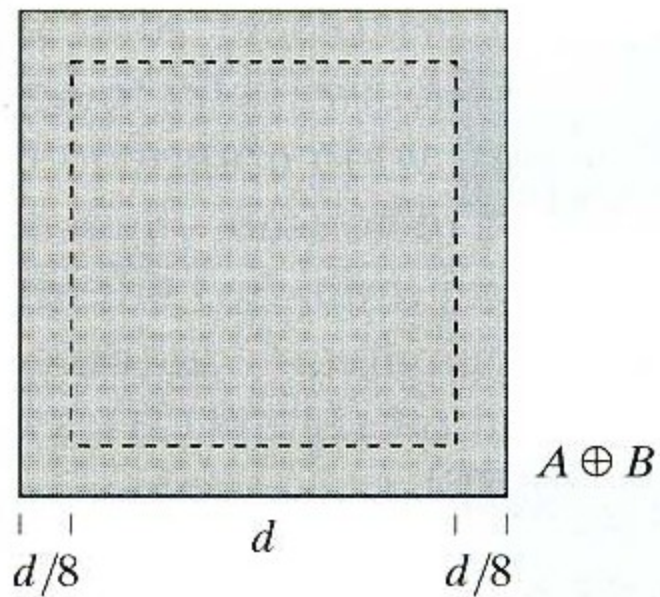
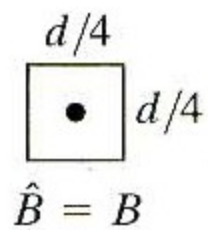
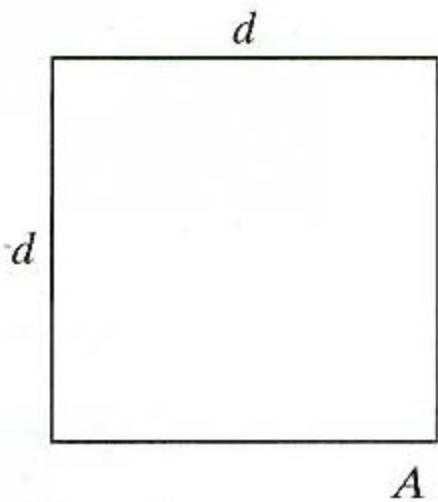
- Dilation and Erosion are two basic operations in morphological processing.
- Dilation of a set A in Z^2 by a set B in Z^2 is denoted by $A \oplus B$ and given by

$$A \oplus B = \{z \mid (\hat{B})_z \cap A \neq \emptyset\}$$

Dilation

- The dilation of A by B is the set of all displacements such that A and \hat{B} overlap with at least one point
- B is called structuring element

Dilation



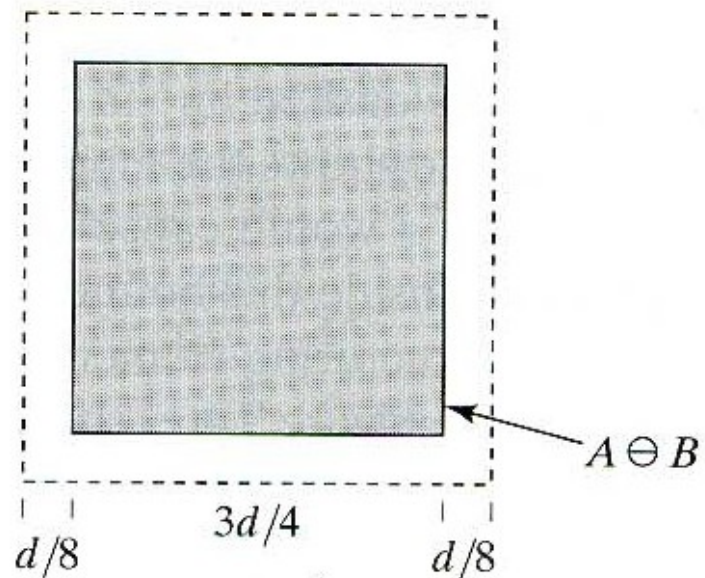
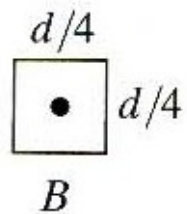
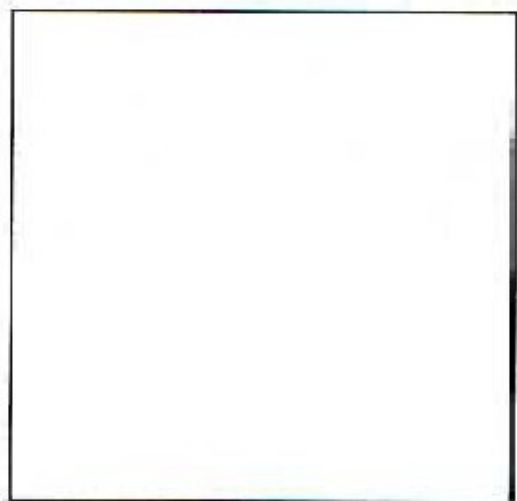
Erosion

- Erosion of a set A in Z^2 by a set B in Z^2 is denoted by $A \ominus B$ and given by:

$$A \ominus B = \{z \mid (B)_z \subseteq A\}$$

Erosion of A by B is the set of all points z such that B translated by z is contained in A

Erosion



Opening

- Opening smoothes the outer contours, breaks narrow connections, and eliminates small protrusions.
- Opening is defined as :

$$A \circ B = (A \ominus B) \oplus B$$

Closing

- Closing smoothes the object contour, fuses narrow connections, eliminates small holes and gaps.

$$A \bullet B = (A \oplus B) \ominus B$$

Extraction of Connected Components

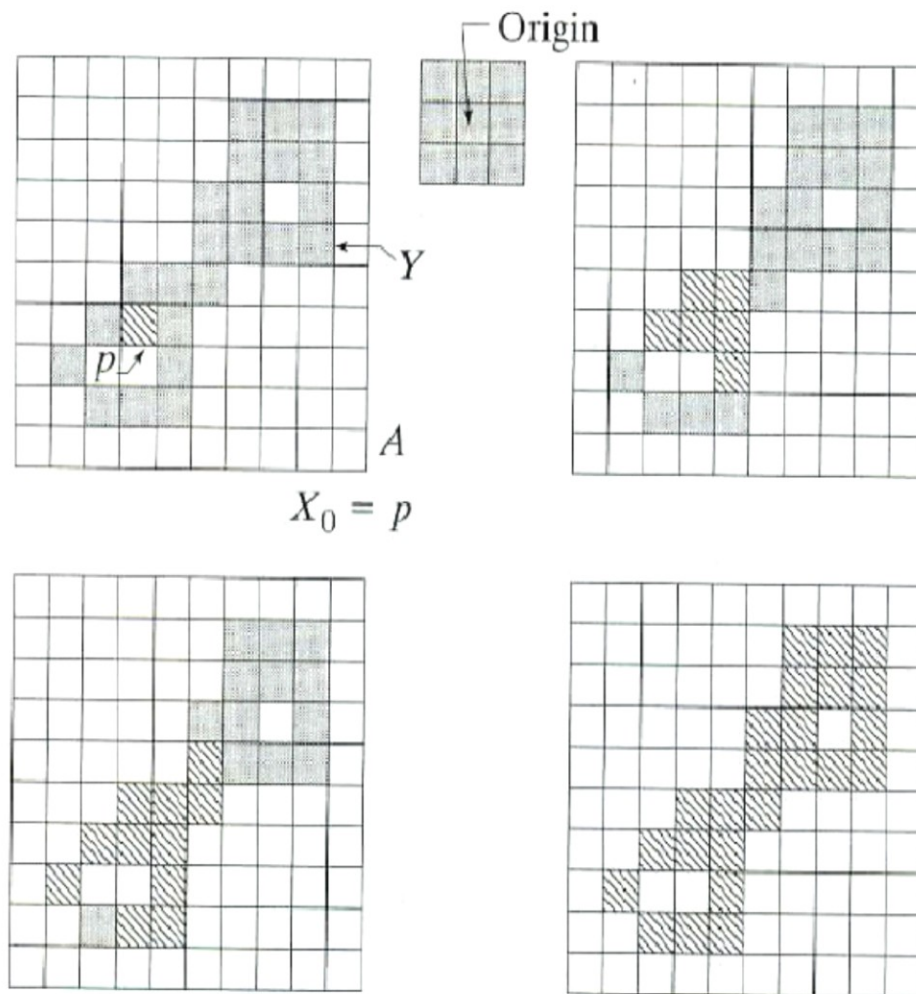
- Begin with a point P inside the connected component, iterate:

$$X_k = (X_{k-1} \oplus B) \cap A \quad k = 1, 2, 3, \dots$$

Until $X_k = X_{k-1}$

Initially $X_0 = P$

Connected Component Extraction

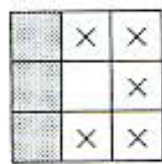


Convex Hull

- A set is said convex if the straight line connecting any two points of the set lies entirely within A.
- Convex Hull of set S is the smallest convex set A that contains S
- The set difference $A-S$ is called the convex deficiency of S

Computing Convex Hull

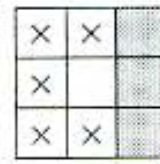
- Let B_i for $i=1,2,3,4$ represent the structuring elements shown below



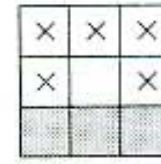
B^1



B^2



B^3



B^4

Convex Hull

- Repeat the following equation until converge

$$X_k^i = (X_{k-1} \circledast B^i) \cup A \quad i = 1, 2, 3, 4 \quad \text{and} \quad k = 1, 2, 3, \dots$$

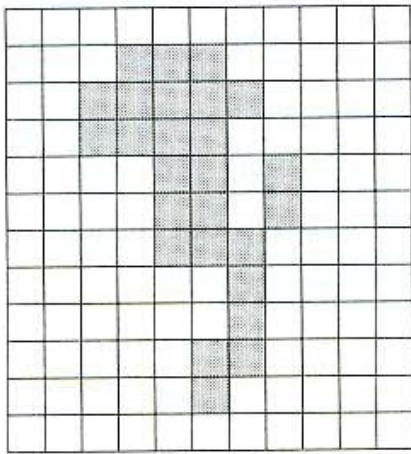
with

$$X_0^i = A$$

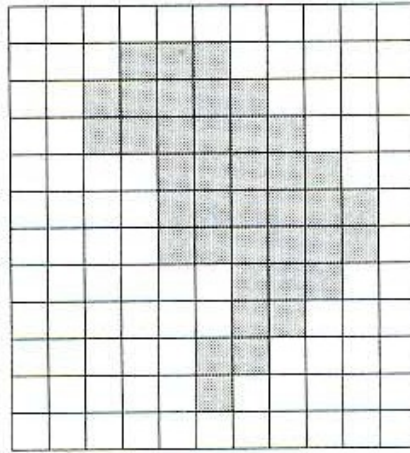
\circledast is the Hit-or-Miss operator

Assuming $D^i = X_{\text{conv}}^i$ Convex Hull is $C(A) = \bigcup_{i=1}^4 D^i$

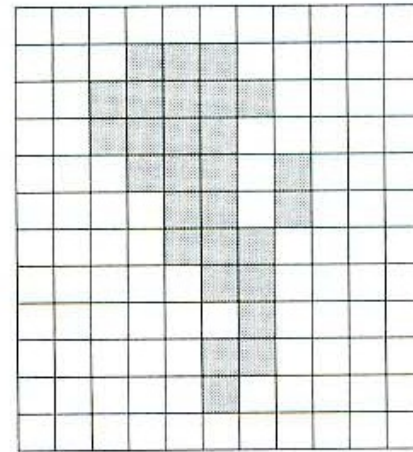
Example (Convex Hull)



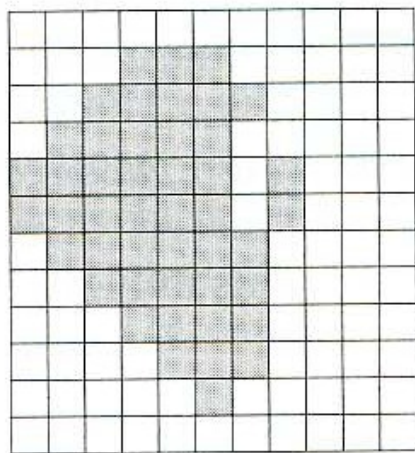
$X_0 = A$



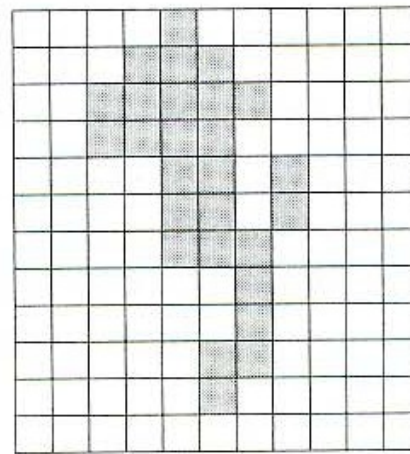
X_4^1



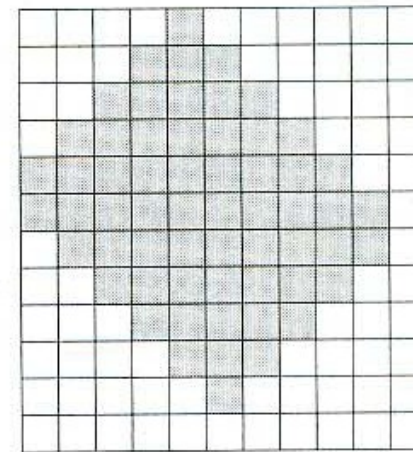
X_2^2



X_8^3



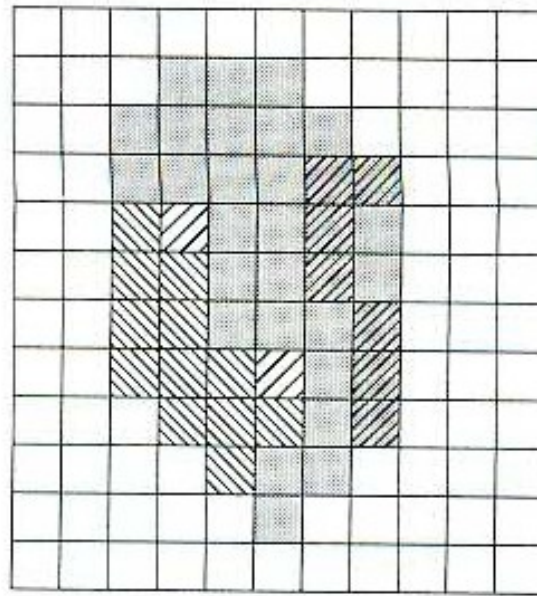
X_2^4



$C(A)$

Improving Convex Hull Algorithm

- The algorithm can be improved by limiting the growth of the algorithm beyond the maximum dimensions of the original set.



Thinning and Thickening

- Thinning is an image-processing operation in which binary valued image regions are reduced to lines
- The purpose of thinning is to reduce the image components to their essential information for further analysis and recognition
- Thickening is changing a pixel from 1 to 0 if any neighbors of the pixel are 1.
- Thickening followed by thinning can be used for filling undesirable holes.
- Thinning followed by thickening is used for determining isolated components and clusters.

Thinning

- Thinning is defined in terms of hit or miss as

$$\begin{aligned}A \otimes B &= A - (A \circledast B) \\ &= A \cap (A \circledast B)^c.\end{aligned}$$

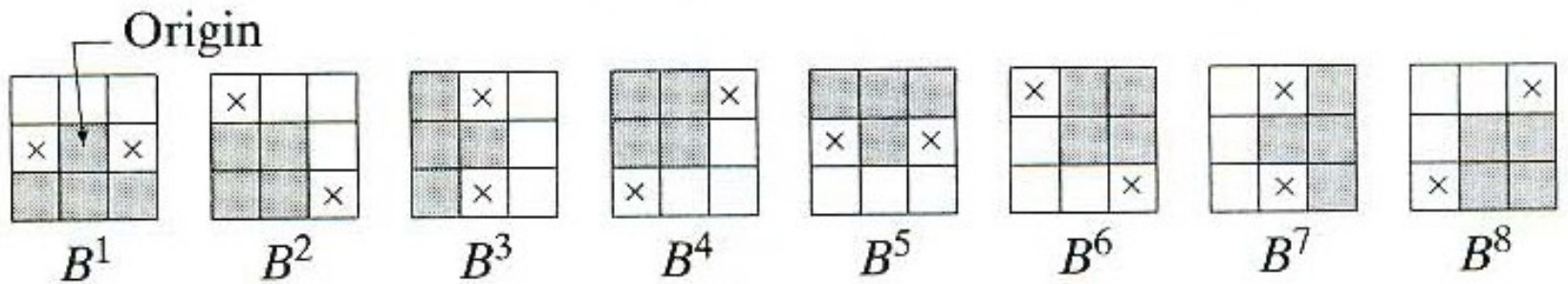
where B is a sequence of structuring elements like

$\{B\} = \{B^1, B^2, B^3, \dots, B^n\}$ and the operation can be given as

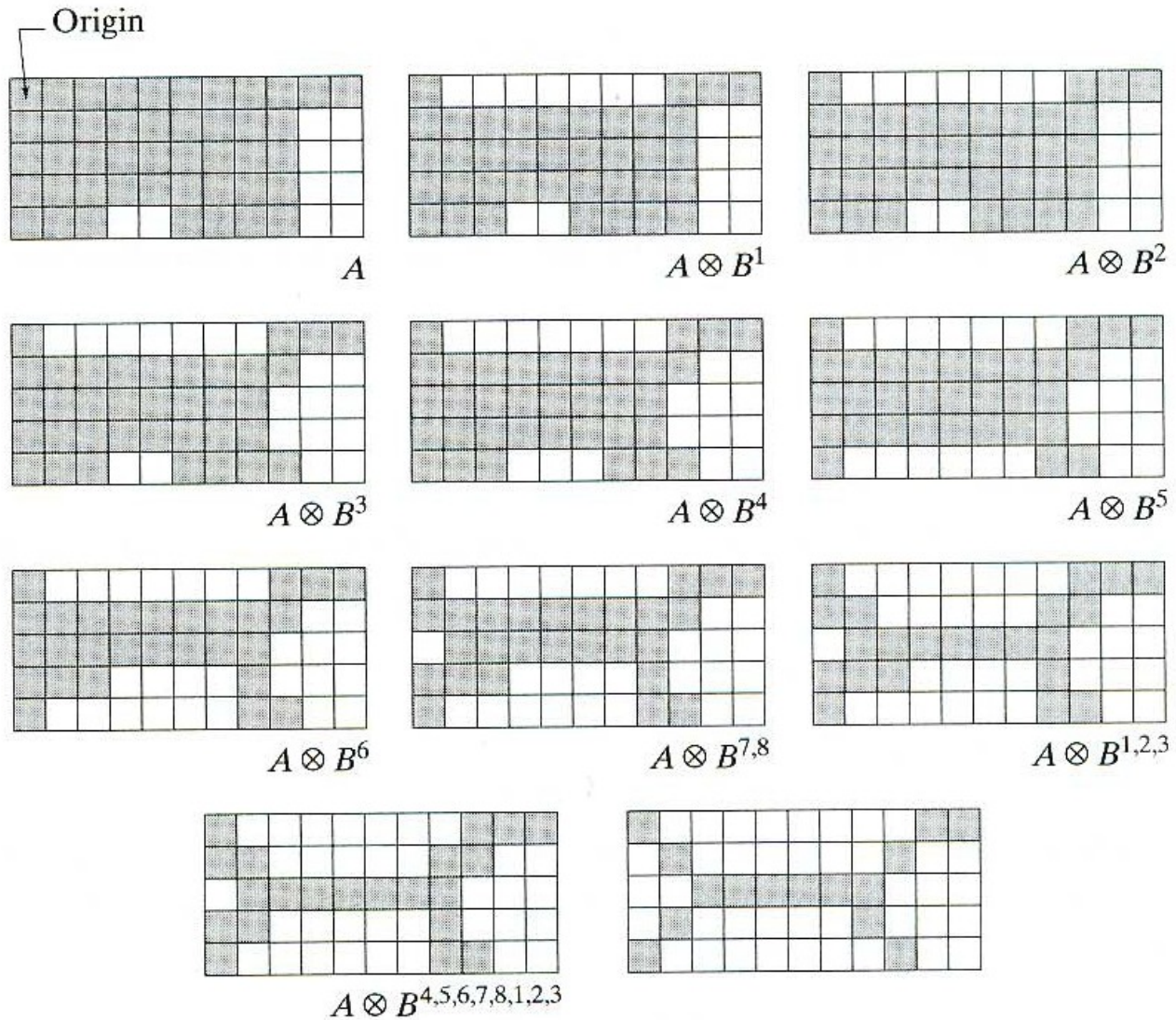
$$A \otimes \{B\} = (((\dots ((A \otimes B^1) \otimes B^2) \dots) \otimes B^n)$$

Thinning

- Sample set of structuring elements



Thinning Example



Thickening

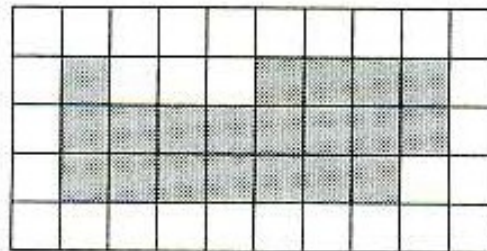
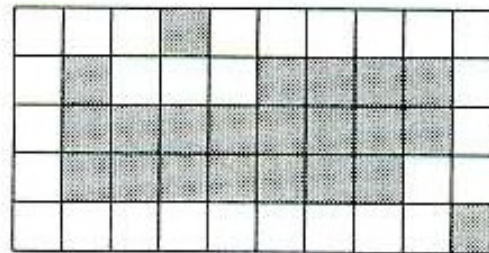
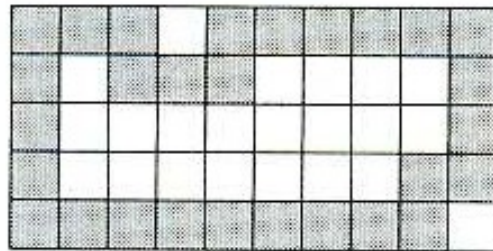
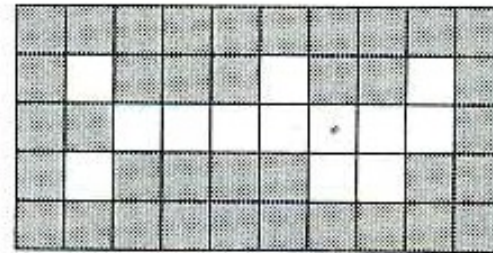
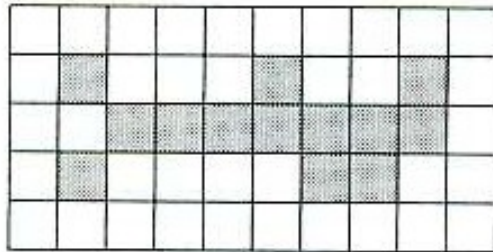
- Thickening is the morphological dual of thinning and defined as

or

$$A \odot B = A \cup (A * B)$$

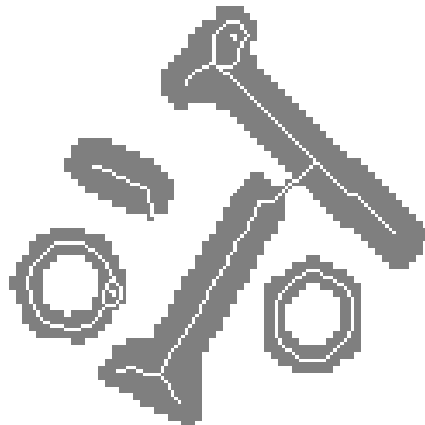
$$A \odot \{B\} = (((\dots ((A \odot B^1) \odot B^2) \dots)) \odot B^n)$$

Thickening Example



Skeleton

- The informal definition of a skeleton is a line representation of an object that is:
 - one-pixel thick,
 - through the "middle" of the object, and,
 - preserves the topology of the object.



Skeleton

- Skeleton is defined by

$$S(A) = \bigcup_{k=0}^K S_k(A)$$

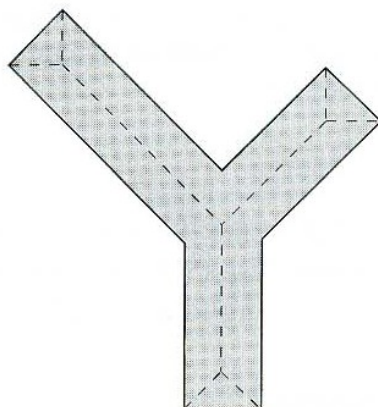
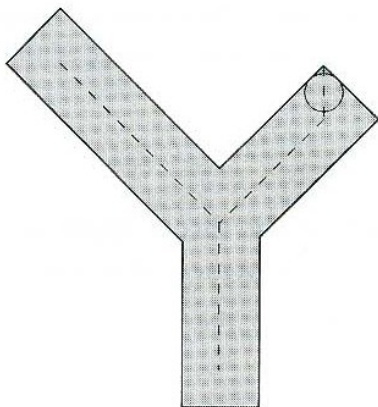
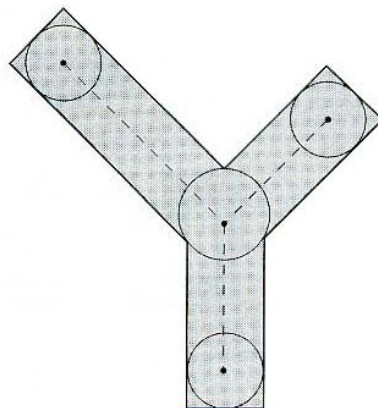
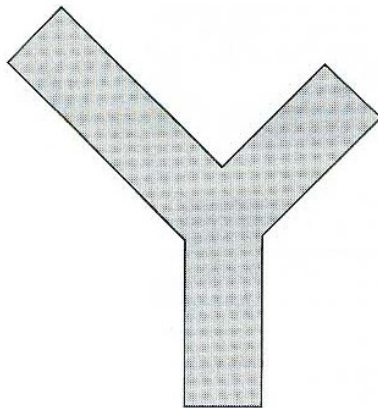
where

$$S_k(A) = (A \ominus kB) - (A \ominus kB) \circ B$$

k is the last iterative step before A erodes to an empty set

$$K = \max\{k \mid (A \ominus kB) \neq \emptyset\}$$

Skeleton Example



Pruning

- Thinning and skeletonizing algorithms need a clean-up post-processing
- The following steps are used for pruning:

- Thinning

$$X_1 = A \otimes \{B\}$$

- Find the end points

$$X_2 = \bigcup_{k=1}^8 (X_1 \circledast B^k)$$

- Dilate end points

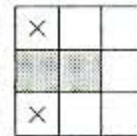
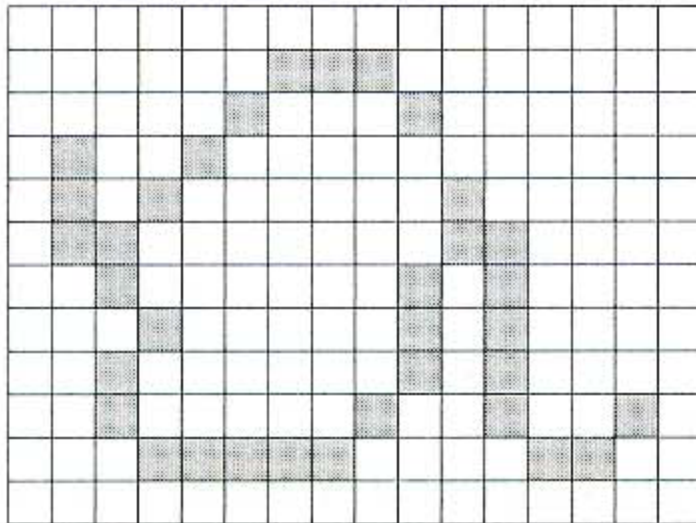
$$X_3 = (X_2 \oplus H) \cap A$$

- Find the union of X_1 and X_3

$$X_4 = X_1 \cup X_3$$

Pruning Example

- Original image and structuring elements



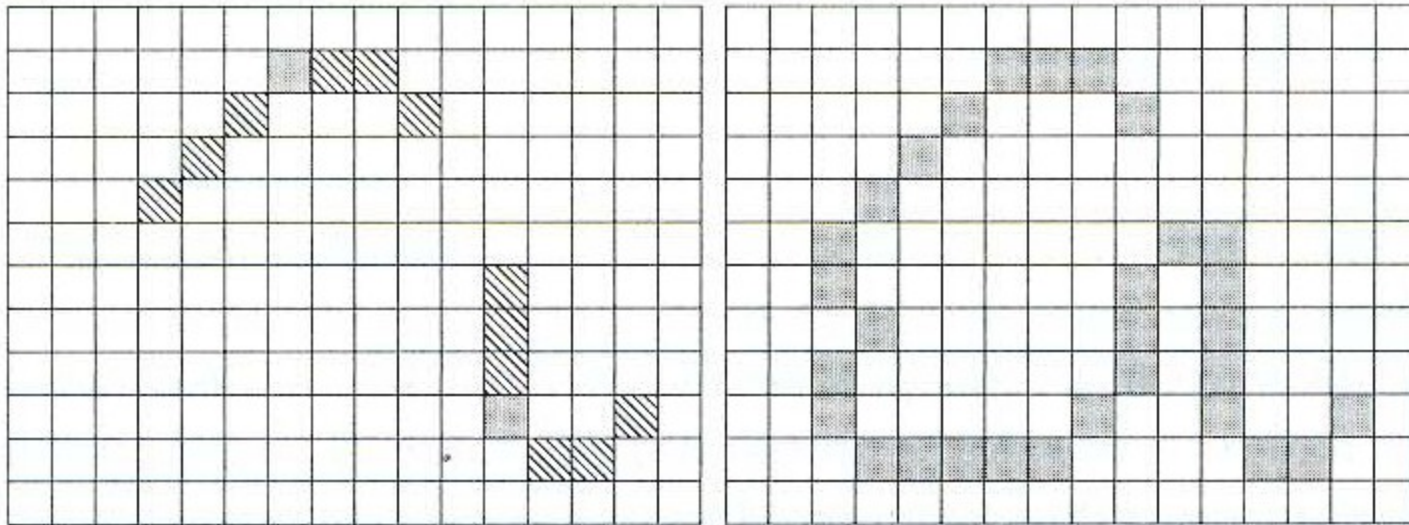
B^1, B^2, B^3, B^4 (rotated 90°)



B^5, B^6, B^7, B^8 (rotated 90°)

Pruning Example

- Dilation of end points and the pruned image



Extension to Gray Level

- Dilation is expressed in 1D as

$$(f \oplus b)(s) = \max \{f(s - x) + b(x) \mid (s - x) \in D_f \text{ and } x \in D_b\}$$

- Erosion is given by

$$(f \ominus b)(s) = \min \{f(s + x) - b(x) \mid (s + x) \in D_f \text{ and } x \in D_b\}$$

Extension to Gray Level (2D Case)

- Dilation

$$(f \oplus b)(s, t) = \max \{ f(s - x, t - y) + b(x, y) \mid (s - x), (t - y) \in D_f; (x, y) \in D_b \}$$

- Erosion

$$(f \ominus b)(s, t) = \min \{ f(s + x, t + y) - b(x, y) \mid (s + x), (t + y) \in D_f; (x, y) \in D_b \}$$

Morphological Operations in MATLAB

- To create structuring element use `strel(.)`

`SE = strel(shape, parameters)`

Examples:

`SE = strel('arbitrary', NHOOD)`

`SE = strel('diamond', R)`

`SE = strel('disk', R, N)`

`SE = strel('line', LEN, DEG)`

`SE = strel('octagon', R)`

`SE = strel('pair', OFFSET)`

`SE = strel('periodicline', P, V)`

`SE = strel('rectangle', MN)`

`SE = strel('square', W)`

Morphological Operations in MATLAB

- `SE=strel(NHOOD)` is also a valid call for the function
- Use `imerode(Im,SE)` and `imdilate(Im,SE)` for erosion and dilation respectively
- Use `imopen(Im,SE)` and `imclose(Im,SE)` for opening and closing
- For hit-or-miss use `bwhitmiss(.)`
 - `BW2 = bwhitmiss(BW1,SE1,SE2)`
 - `BW2 = bwhitmiss(BW1,INTERVAL)`

Hit or Miss Example

```
bw = [0 0 0 0 0 0
      0 0 1 1 0 0
      0 1 1 1 1 0
      0 1 1 1 1 0
      0 0 1 1 0 0
      0 0 1 0 0 0]
```

```
interval = [0 -1 -1
            1  1 -1
            0  1  0];
```

```
bw2 = bwhitmiss(bw, interval)
```

```
bw2 =
```

```
0 0 0 0 0 0
0 0 0 1 0 0
0 0 0 0 1 0
0 0 0 0 0 0
0 0 0 0 0 0
0 0 0 0 0 0
```

Questions?